



UNIVERSITÀ DI PISA

DIPARTIMENTO DI INGEGNERIA STRUTTURALE

**Dottorato in Ingegneria delle Strutture**

*Stefano Bennati (Presidente del Corso)*

*Via Diotisalvi, 2 – I 56126 PISA*

*Tel. +39 050 835711 – Fax +39 050 554597*

*E-mail: s.bennati@ing.unipi.it*

## A V V I S O D I S E M I N A R I

*Nell'ambito delle iniziative promosse dal Dottorato in Ingegneria delle Strutture  
e dal Dottorato in Ingegneria Aerospaziale,*

il Prof. **Gianpietro Del Piero**, dell'Università di Ferrara ed  
il Prof. **Jean-Jacques Marigo**, dell'Université Paris 6,

*terranno i due seminari seguenti:*

### **1) Introduzione alla teoria della frattura di G. Francfort e J.J. Marigo**

*(Gianpietro Del Piero, **martedì 13 giugno, ore 17.00**)*

**Sommario.** Il seminario ha per oggetto una breve illustrazione della teoria della frattura di un corpo elastico dovuta a G. Francfort ed a J.J. Marigo. Secondo la formulazione data in [Francfort & Marigo, 1998], il problema della frattura è ridotto al problema di minimo di un funzionale energia costituito da due termini: un'energia a densità volumetrica, dipendente in maniera quadratica dal gradiente di deformazione, e un'energia a densità superficiale, proporzionale all'area della superficie di frattura. Seguendo l'evoluzione della deformazione al variare di un parametro di carico, è possibile sia predirne la formazione della frattura che seguirne la propagazione.

Ciò è possibile grazie alla tecnica risolutiva messa a punto in [Ambrosio & Tortorelli, 1990], basata sull'approssimazione del funzionale energia, che è definito sulle funzioni a variazione limitata mediante una famiglia di funzionali più regolari, definiti sugli ordinari spazi di Sobolev. La convergenza dei funzionali approssimanti è assicurata nel senso della Gamma-convergenza. Verranno illustrati alcuni risultati ottenuti in [Bourdin, Francfort & Marigo, 2000] su problemi modello bidimensionali. Si fornirà infine un breve cenno alla recente estensione del modello al problema della fatica [Jaubert & Marigo, in stampa].

### **2) A variational approach to fracture: the evolution of cracks seen as an energy minimization problem**

*(Jean-Jacques Marigo, **mercoledì 14 giugno, ore 11.00**)*

**Abstract.** Griffith proposed in his famous paper to base the propagation of cracks on a principle of least energy. Many researchers and engineers develop their works from this idea.

Unfortunately, the Griffith theory leads on a too simple assumption concerning the surface energy associated with a crack. With his assumption, we cannot account for various physical phenomena, like the initiation of cracks or the propagation of cracks by fatigue. To correct these drawbacks, we must change the form of the surface energy and introduce the concept of cohesive forces. On the other hand, several fundamental issues appear like the question of the irreversibility or the issue of the microcracking. In my seminar, I will try to present the basic ingredients of this variational theory of fracture, the most important results that we have obtained and also some still open problems.

Referenti dell'invito: Stefano Bennati, Aldo Frediani e Paolo S. Valvo.

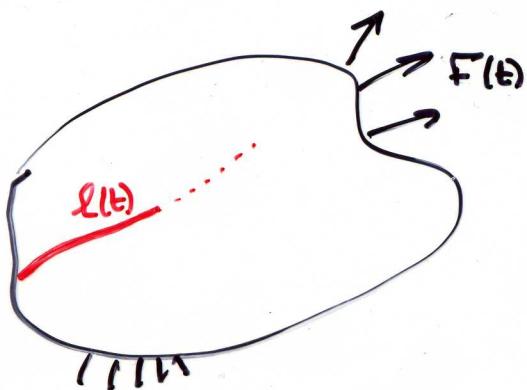
I seminari saranno tenuti nella sala riunioni del DIS.

Pisa, 7 giugno 2006

Il Coordinatore del Corso di Dottorato

*(Prof. Stefano Bennati)*

## GRIFFITH THEORY =



A surface energy assumption

$$G_c$$

+

A criterion of propagation

$$(G - G_c) \dot{e} \geq 0$$

$$\dot{e} \geq 0, \quad E \leq G_c$$

+ An irreversibility criterion

Remark Griffith law  $\approx$  An Optimality condition  
for a restricted family  
of cracks

Potential Energy

$$E_p(l, t) = \min_{u \in \mathcal{C}(l, t)} \left\{ \frac{1}{2} \int_{S_E} A \epsilon(u) \cdot \sigma(u) d\Gamma - f_t(u) \right\}$$

Energy Release Rate

$$G = - \frac{\partial E_p}{\partial l}(l, t)$$

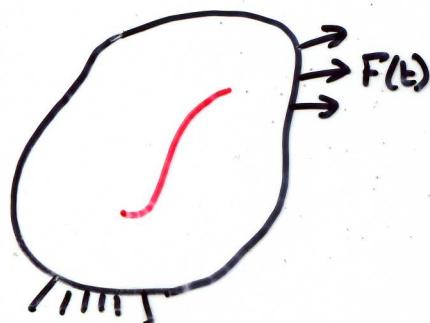
Total Energy

$$E(l, t) = E_p(l, t) + G_c l$$

$l(t)$  : "local minimum"  $E(l, t)$   
(with irreversibility)

# A variational approach of fracture

From GRIFFITH to PARIS  
via BARENBLATT



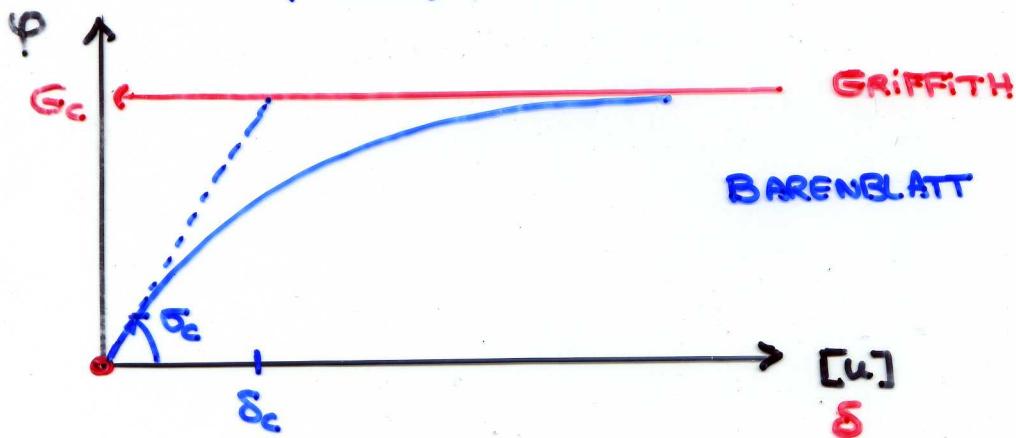
Elasticity + "CRACKS"

$u(\epsilon)$  ?

$S_u(\epsilon)$  ?



(Global)  
(Local) Minimization of the "total" energy



## Some issues

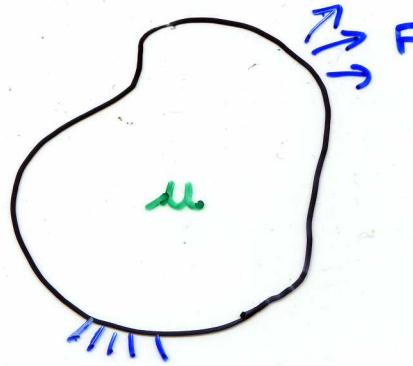
- The INITIATION of CRACKS
- The CONCEPT of PROCESS ZONE
- The IRREVERSIBILITY of CRACK PROPAGATION
- The PHENOMENON of FATIGUE

CONTEXT :

- LINEAR ELASTICITY - SMALL DISPLACEMENTS
- QUASI-STATIC - RATE INDEPENDENT PROCESSES
- DYNAMICS

## Initiation of crack with GRIPPITH theory?

(2)

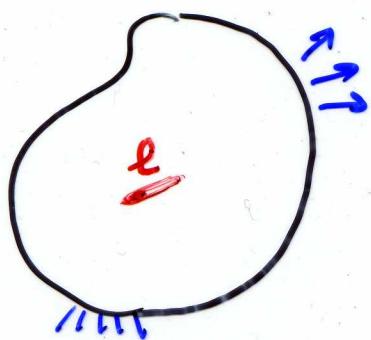


$$u \quad \text{Min}_{v} \left\{ \int_{\Omega} W(\epsilon(v)) dx - F(v) \right\}$$

convex "small strains"

$\downarrow$

$s_u, s_v = \phi$



$$u_l \quad \text{Min}_{v} \left\{ \int_{\Omega_l} W(\epsilon(v)) dx - F(v) \right\}$$

$s_{u_l}, s_v \subset \text{"crack } l"$

$$E(u)$$

"

? //

$$E(u_l)$$

"

For small  $l$

$$\int_{\Omega} W(\epsilon(u)) dx - F(u)$$

$\underbrace{\qquad\qquad\qquad}_{S_0}$

$S_0$

$$\int_{\Omega_l} W(\epsilon(u_l)) dx - F(u_l) + G_c l$$

$\underbrace{\qquad\qquad\qquad}_{S_l}$

$S_l$

In general

$$S_l = S_0 + o(l), \quad \lim \frac{o(l)}{l} = 0.$$

Conclusion

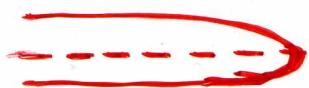
The release of potential energy  
is too small. In comparison to surface energy.



The elastic response is a local minimum,  $\nabla F$

# Initiation of cracks with BARENBLATT theory !

## GRIFFITH defects



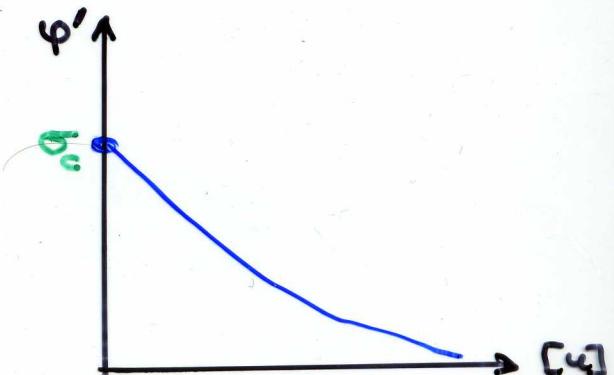
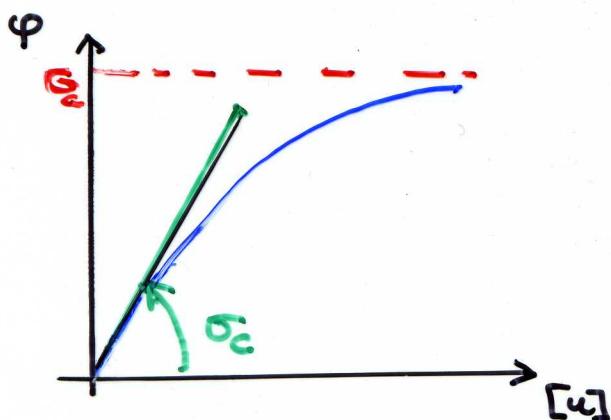
stress singularity

smooth crack opening

## BARENBLATT corrections



## variational approach (Del Piero)



$$E_s(u) = \int_{S_u} \Phi([u]) \, ds$$

$$\min_u \{ E_b(u) + E_s(u) - W_e(u) \}$$

Barenblatt energy

+

Local Minimum



Equilibrium

+

Cohesive Forces

+

Stress yield



+

Stability

$$E(u+\delta v) = E(u) + \delta F(u; v) + \frac{\delta^2}{2} G(u, v) + \dots$$

1<sup>st</sup> order

$$F(u; v) \geq 0 \quad \forall v \text{ "admissible"}$$

2<sup>nd</sup> order

$$G(u, v) \geq 0 \quad \forall v \text{ "admissible"}$$

$$F(u, v) = 0$$

- Energie de Barensfeldt

+

- Minimum local

$\Rightarrow$

- Equilibre

+

- Seuil en contrainte

Preuve. (Hypothèse : 1D ;  $[u] \geq 0$ )

$$(*) \quad 0 \leq DE(u)(v) = \int_{\Omega \setminus S(u) \cup S(v)} \sigma' v' dx + \sum_{S(u) \cup S(v)} \varphi'([u]) [v] - f(v)$$

$A_u'$   
"

$\forall v$  admissible.

$$(1) \quad S(v) = \emptyset \quad \rightarrow$$

$$\sigma' + f = 0 \quad \text{dans } \Omega \setminus S(u)$$

$$\sigma = F \quad \text{sur } \partial_F \Omega$$

Equilibre

$$(*) \quad 0 \leq \sum_{S(u) \cup S(v)} (\varphi'([u]) - \sigma) [v], \quad \forall v \text{ admissible}$$

$$(2) \quad S(v) \subset S(u) \quad (\Rightarrow [v] \text{ arbitraire sur } S(u))$$

$$\rightarrow \quad \boxed{\sigma = \varphi'([u]) \quad \text{sur } S(u)}$$

Forces de cohésion

$$(*) \quad 0 \leq \sum_{S(v) \setminus S(u)} (\varphi'(0) - \sigma) [v], \quad \forall v \text{ admissible}$$

$$(3) \quad S(v) \setminus S(u) = \{x_0\} \quad (\Rightarrow [v](x_0) > 0)$$

$$\rightarrow \quad \boxed{\sigma \leq \varphi'(0) = \sigma_c \quad \text{dans } \Omega \setminus S(u)}$$

Seuil en contrainte

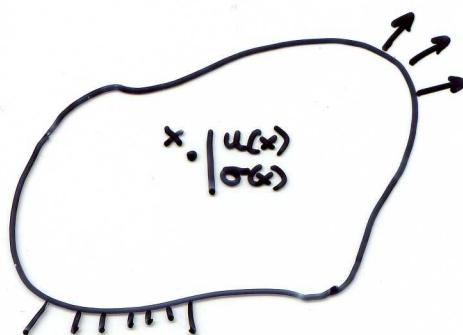
In 3D . H1. Isotropic material

$$\varphi(\delta, n) = \phi(\delta \cdot n, \|\delta - \delta \cdot n\|)$$

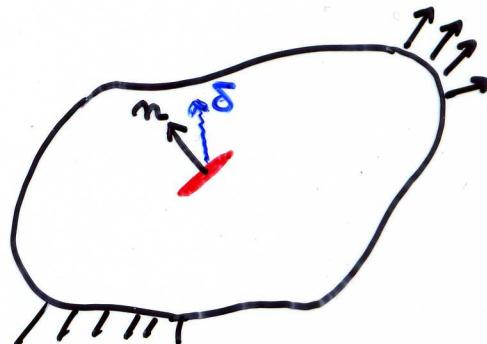
- H2.  $\phi$  smooth ,  $\phi(0,0) = 0$

$$\lim_{h \rightarrow 0^+} \frac{1}{h} \phi(h\alpha, h\beta) = \sigma_c \alpha + \tau_c \beta$$

- H3. Non interpenetration :  $\delta \cdot n > 0$



Elastic response



$$\varepsilon(u) \leq \varepsilon(u + \rho w)$$

$$\varepsilon(v) = \int_{\Omega \setminus S_v} A \varepsilon(v) \cdot \varepsilon(v) dx + \int_{S_v} \Phi([v], n_v) dS - (f, v)$$



$$\sigma(x) n \cdot \delta \leq \sigma_c \delta \cdot n + \tau_c \|\delta - \delta \cdot n\| \quad \forall x, \forall n, \forall \delta$$



$$\text{up } \sigma_i \leq \sigma_c$$

Maximal traction

$$\text{up } \sigma_i - \sigma_j \leq \tau_c$$

Maximal shear

Case 1 :  $\Phi$  differentiable at  $(0,0)$

$$\phi'(\alpha, \beta) = \sigma_c \alpha + \tau_c \beta$$

$\downarrow$   
material constants ( $> 0$ )

$$\sigma_n \cdot \delta \leq \sigma_c \delta \cdot n + \tau_c \|\delta - \delta_{n,n} n\|$$

$\forall n, \delta ; \quad \delta \cdot n \geq 0$



$$\sup_i \sigma_i \leq \sigma_c \quad \text{and}$$

$$\sup_i \{\sigma_i - \sigma_0\} \leq \tau_c$$

Maximal Traction

Maximal Shear

Remark

Independent of the form of  $\Phi$   
(except isotropy + regularity)

Case 2 :  $\Phi$  admits directional derivatives

- $\phi'(\alpha, \beta)$  positively homogeneous of degree 1 in  $(\alpha, \beta)$
- $\alpha \geq 0, \beta \geq 0$

$\sigma_n \cdot \delta \leq \phi'(\delta \cdot n, \| \delta - \delta_m n \|), \quad \delta \cdot n \geq 0$

(i)  $\delta \parallel n$

$$\begin{aligned} \textcircled{\times} \Rightarrow \quad & \sigma_n \cdot n \leq \phi'(1, 0) = \sigma_c, \quad \forall n : \|n\|=1 \\ \Rightarrow \quad & \sup_i \sigma_i \leq \sigma_c \end{aligned}$$

(ii)  $\delta = \alpha n + t$ ,  $t \cdot n = 0$ ,  $\alpha \geq 0$ .

$$\textcircled{\times} \Rightarrow |\sigma_n \cdot t| \leq \phi'(\alpha, 1) - \alpha \sigma_n \cdot n, \quad \forall \alpha \geq 0, \quad \forall n : \|n\|=1$$

$$\begin{aligned} \Rightarrow |\sigma_n \cdot t| &\leq - \sup_{\alpha \geq 0} \{ \alpha \sigma_n \cdot n - \phi'(\alpha, 1) \} \\ &= - \psi^*(\sigma_n \cdot n) \end{aligned}$$

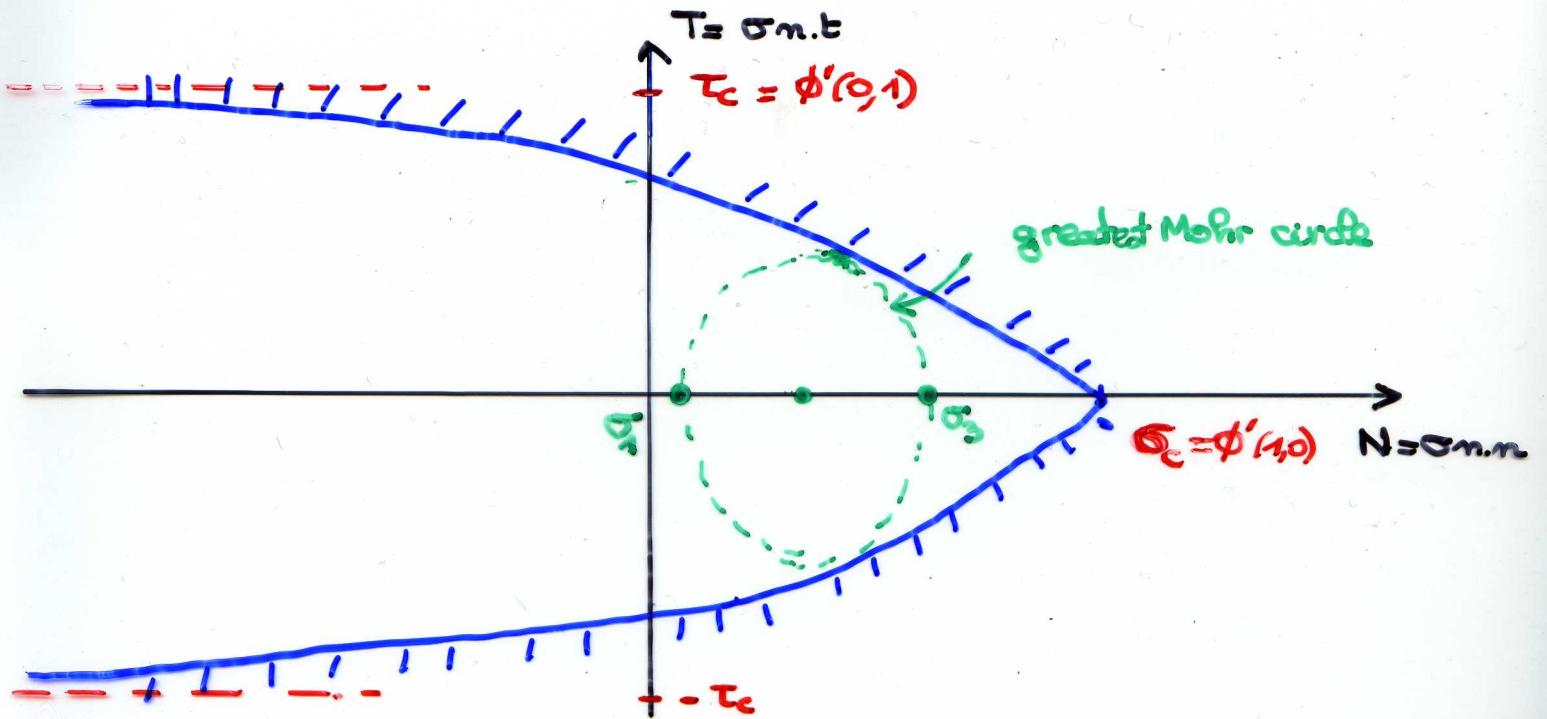
↑

Legendre transform of  $\phi'(\cdot, 1)$

$I_{R^+}^+$

Intrinsic curve

$$|\sigma_n \cdot t| + \psi^*(\sigma_n \cdot n) \leq 0 \quad \forall n, t : n \cdot t = 0$$



Conclusion

$$|\sigma_3 - \sigma_1| + 2 \Psi_* \left( \frac{\sigma_1 + \sigma_3}{2} \right) \leq 0$$

$$\Psi_* (\omega) = \sup_{\omega \in [0, \pi/2]} \{ \Delta \cos \omega - \phi'(\cos \omega, \sin \omega) \}$$

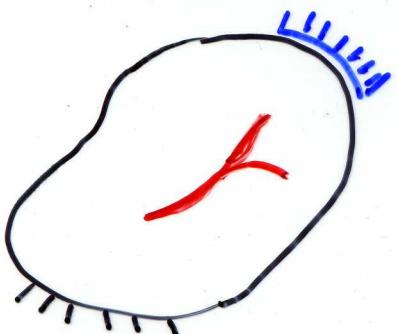
Envelop of greatest Mohr circles

## The CONCEPT of PROCESS ZONE

"

### Relaxation of the energy

#### 1. WITH GRIFFITH

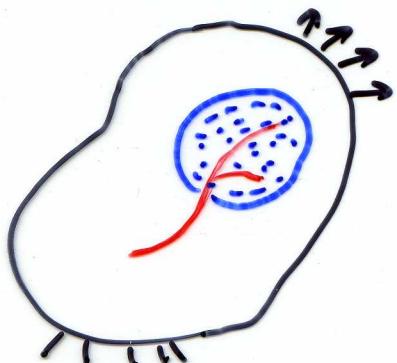


Existence of the Minimum

"

No PROCESS ZONE

#### 2. with BARENBLATT



No existence of the Minimum

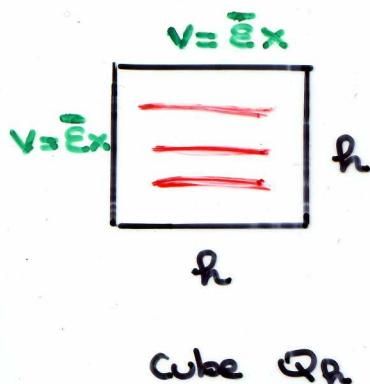
"

PROCESS ZONE

"

FINE MIXTURE  
of  
Elastic deformation  
and  
MICRO JUMPS

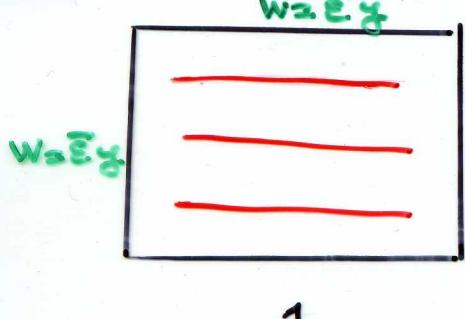
## Effective bulk energy



$$\text{vol}(Q_h) W_h^{\text{eff}}(\bar{E}) = \min_{\substack{v = \bar{E}x \\ \text{on } \partial Q_h}} \left\{ \int_{Q_h \setminus S_v} W(\varepsilon(v)) dx + \int_{S_v} \Phi(\varepsilon(v)) dS \right\}$$

### Rescaling

$$y = \frac{x}{h} \quad w(y) = \frac{v(x)}{h}$$



$$W_h^{\text{eff}}(\bar{E}) = \min_{\substack{w = \bar{E}y \\ \text{on } \partial Q}} \left\{ \int_{Q \setminus S_w} W(\varepsilon(w)) dy + \int_{S_w} \frac{\Phi(h[\varepsilon(w)])}{h} dS \right\}$$

"At the limit"  $h \rightarrow 0$

$$W^{\text{eff}}(\bar{E}) = \min_{\substack{w = \bar{E}y \\ \text{on } \partial Q}} \left\{ \int_{Q \setminus S_w} W(\varepsilon(w)) dy + \int_{S_w} \phi'([w]_m, || \dots ||) dS \right\}$$



Bouchitte et al. Definition

### Lower bound

$$\begin{aligned}
 W^{\text{eff}}(\bar{\epsilon}) &= \inf_w \left\{ \int_{Q \setminus S_w} W(\epsilon(w)) dy + \int_{S_w} \phi'(\dots) \right\} \\
 &= \inf_w \sup_{\tau} \left\{ \int_{Q \setminus S_w} (\tau \cdot \epsilon(w) - W^*(\tau)) dy + \int_{S_w} \phi'(\dots) \right\} \\
 &\geq \sup_{\tau} \inf_w \left\{ \dots \right\} \\
 &\geq \sup_{\sigma \in \mathbb{M}_3^3} \left\{ \sigma \cdot \bar{\epsilon} - W^*(\sigma) + \inf_{\substack{w: \\ w=0 \\ \text{on} \\ \partial Q}} \int_{S_w} (\phi'(\dots) - \sigma \cdot [w]) ds \right\} \\
 &\quad \underbrace{- I_K(\sigma)}_{\substack{\text{Indicatrix function of} \\ \text{"Admissible stress} \\ \text{convex set}}} \\
 \rightarrow \boxed{W^{\text{eff}} \geq (W^* + I_K)^*}
 \end{aligned}$$

Upper bound : construction of a "good" family of  $w$ .

$$\rightarrow \dots \leq \dots$$

## The issue of irreversibility

- Introduction of a MEMORY variable
- Modification of the MINIMIZATION procedure

### 1. With GRIFFITH

$$\text{"crack"} \quad \Gamma(t) = \bigcup_{0 \leq t} S_{u(\omega)} \supset S_{u(t)}$$

- The memory variable =  $\Gamma$
- The INCREMENTAL Problem

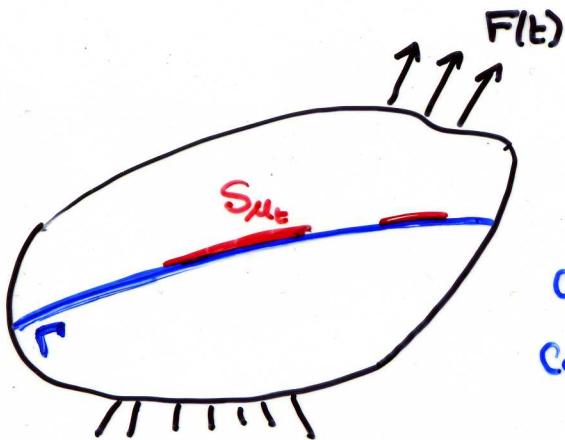
$\Gamma_0$  given

$$\left\{ \begin{array}{l} u_i : \min_{u \in \mathcal{C}_i} \left\{ \int_{\Omega \cap S_u} \frac{1}{2} A \epsilon(u) \cdot \epsilon(u) dx + G_c \mathcal{H}^2(S_u \setminus \Gamma_{i-1}) \right\} \\ \Gamma_i = \Gamma_{i-1} \cup S_{u_i} \end{array} \right.$$

- The "continuous in time" problem (Francfort-Larsen, Del Piero,...)
- =  $\lim_{\Delta t \rightarrow 0}$  Incremental problem

2. With BARENBLATT

(Restricted context:  $S_u \subset \Gamma$  fixed)



Memory variables

Cumulated Opening

$$\delta_m = ([\dot{u}] \cdot n)^+$$

Cumulated Sliding

$$\delta_T = \| [\dot{u}_T] \|$$

Remark: Other choices?

→ Density surface energy  $\phi(\delta_m, \delta_T)$

### The INCREMENTAL PROBLEM

- $\delta_m^0, \delta_T^0, u^0$  given
- $u^i$ : Min  $\left\{ \frac{1}{2} \int_{\Omega \cap \Gamma} \Lambda \epsilon(v) \cdot \epsilon(v) dx + \int_{\Gamma} \phi(\delta_m^{i-1} + ([v - u^{i-1}] \cdot n)^+, \| \delta_T^{i-1} - [v - u^{i-1}] \|) ds - f^i(v) \right\}$
- $\delta_m^i = \delta_m^{i-1} + ([u^i - u^{i-1}] \cdot n)^+, \quad \delta_T^i = \delta_T^{i-1} + \| [u_T^i - u_T^{i-1}] \|$

OPEN PROBLEMS : - Relaxation ?  
-  $\lim_{\Delta t \rightarrow 0}$  ?