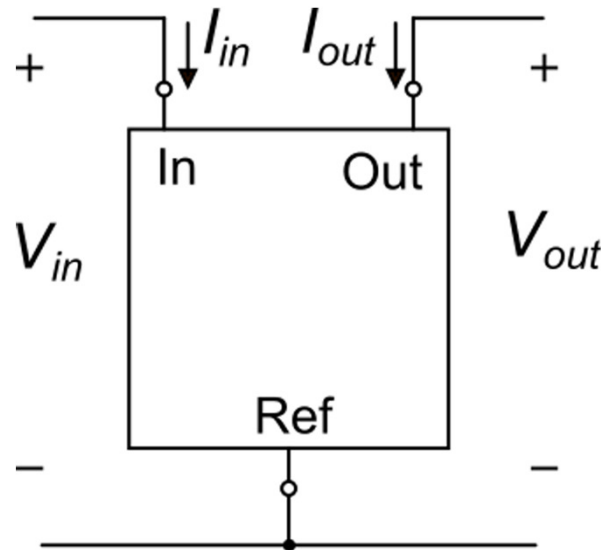
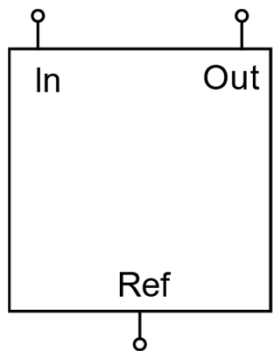


# Current Mirrors: general definitions and properties



Desired characteristics

$$V_{in} = 0$$

$$I_{out} = k_M I_{in}$$

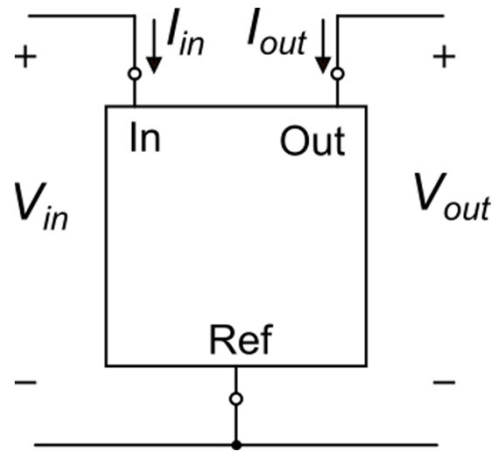
for:

$$-I_{max} < I_{in} < I_{max}$$

$$-V_{max} < V_{out} < V_{out}$$

These characteristics are generally non feasible with simple elementary circuits. They can be obtained with complex architectures (current amplifiers) not with current mirrors.

## Current mirrors: n-type and p-type mirrors



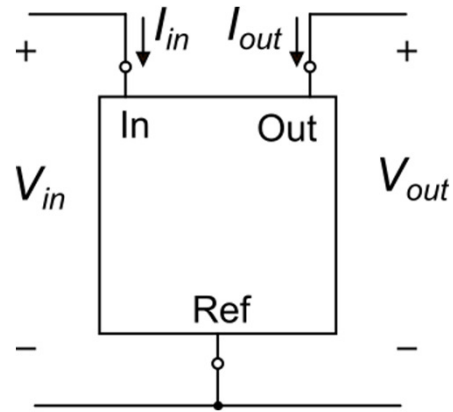
$$I_{out} = k_M I_{in}$$

$V_{out}, V_{in} > 0$  **n-type:**  
 $I_{out}, I_{in} > 0$  formed mainly by n-type transistors

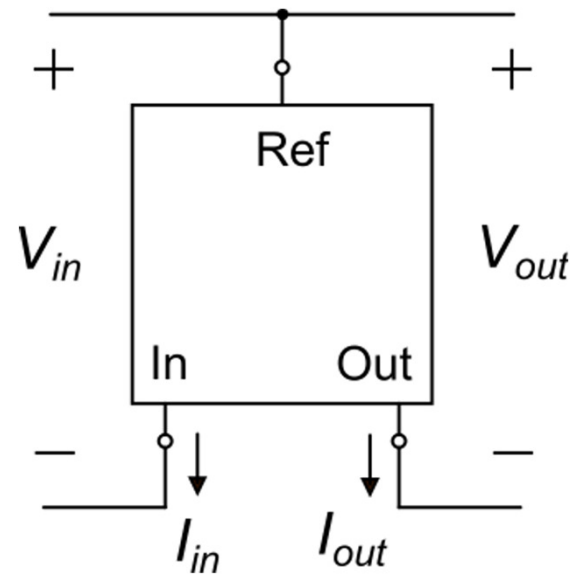
$$k_M > 0$$

$V_{out}, V_{in} < 0$  **p-type:**  
 $I_{out}, I_{in} < 0$  formed mainly by p-type transistors

Conventions on voltage and current signs used to obtain positive values also for p-type mirrors



Convention for an n-type current mirror

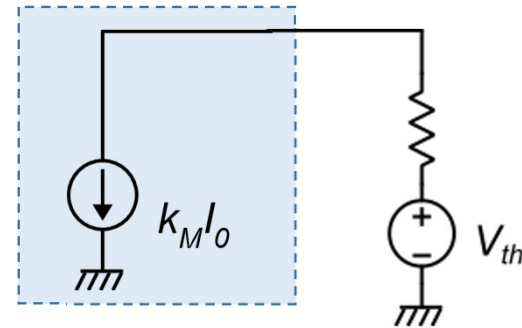
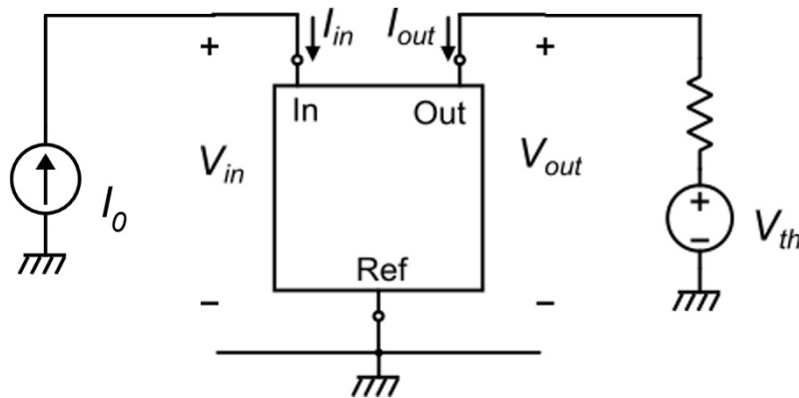


Convention for a p-type current mirror

With this convention all quantities are positive also for the p-type mirror

# Current reversing function of a current mirror

Equivalent circuit seen from the mirror output terminal



This is a current **source** (the current exits from the generator)

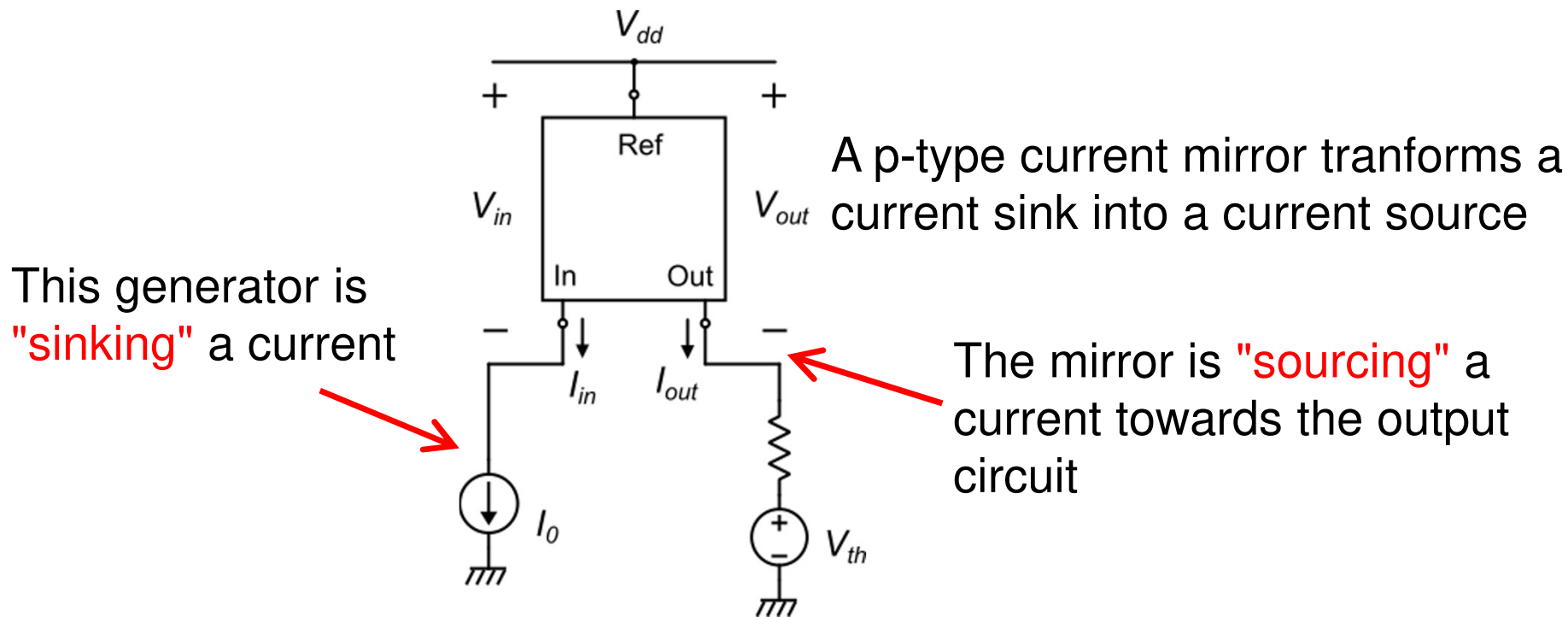
n-type mirror is required (the input current enters the mirror)

The circuit connected to the output port must be able to provide a positive  $V_{out}$

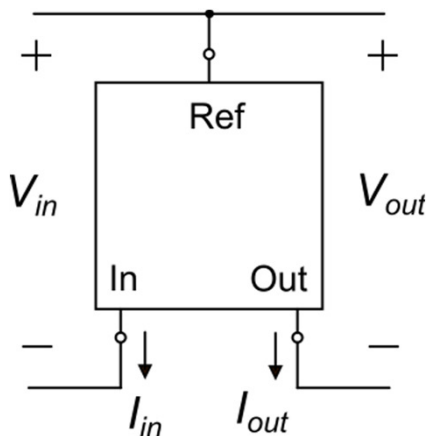
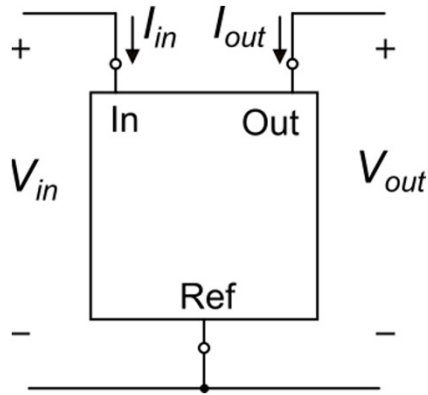
The mirror is seen by the output circuit as an equivalent current source. Note that now the current enters the source (**=sink**)

## Current reversing function of a current mirror

An n-type current mirror transforms a current source (the current exit from the source) into a current sink (the current enter the source)



## Parameters of merit for a current mirror



Ideal function:  $I_{out} = k_M I_{in}$

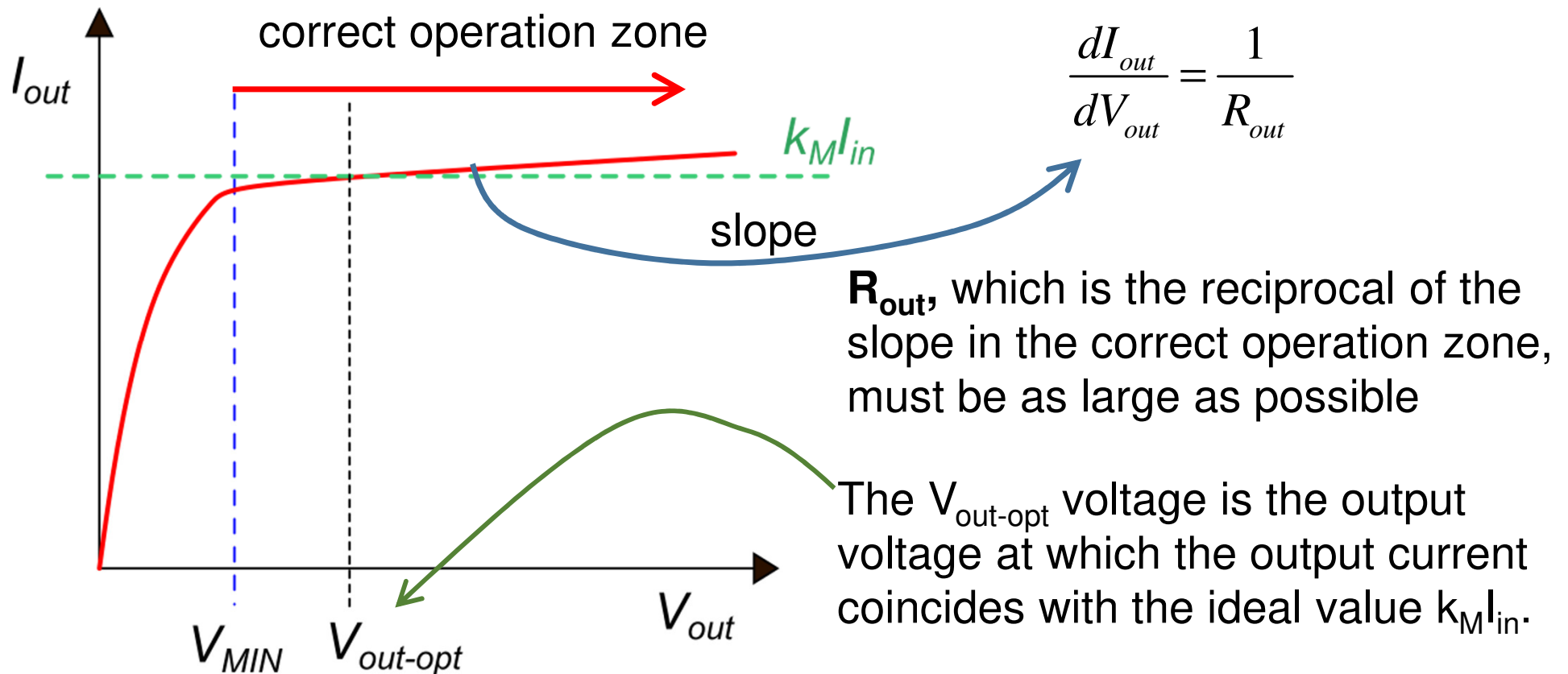
General conditions

$$V_{out}, V_{in} > 0$$

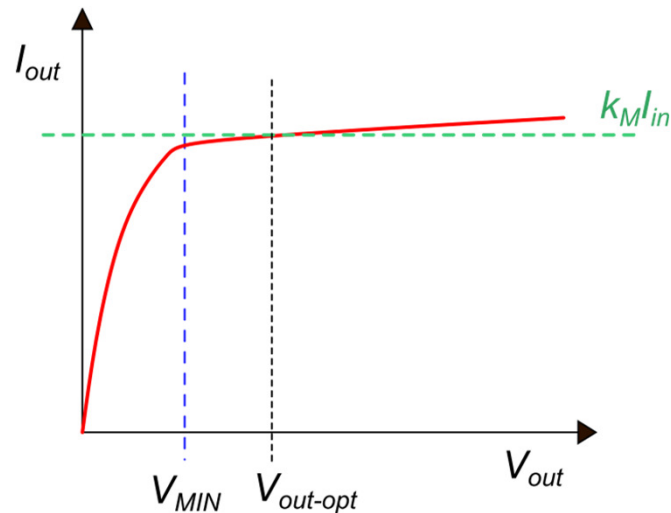
$$I_{out}, I_{in} > 0$$

1.  $V_{in}$  should be almost constant and be as small as possible
2. The ideal function should be maintained down to very small  $V_{out}$  values. The smallest  $V_{out}$  value is indicated with  $V_{MIN}$
3. For  $V_{out} > V_{MIN}$ , the dependence of  $I_{out}$  on  $V_{out}$  must be the smallest as possible.

# The typical $I_{out}$ vs $V_{out}$ characteristic of a current mirror



## The mirror "Thevenin" voltage, $V_{th}$



definition:  $V_{th} = I_{out} R_{out}$

current variation:  $\Delta I_{out} = \Delta V_{out} \frac{1}{R_{out}}$

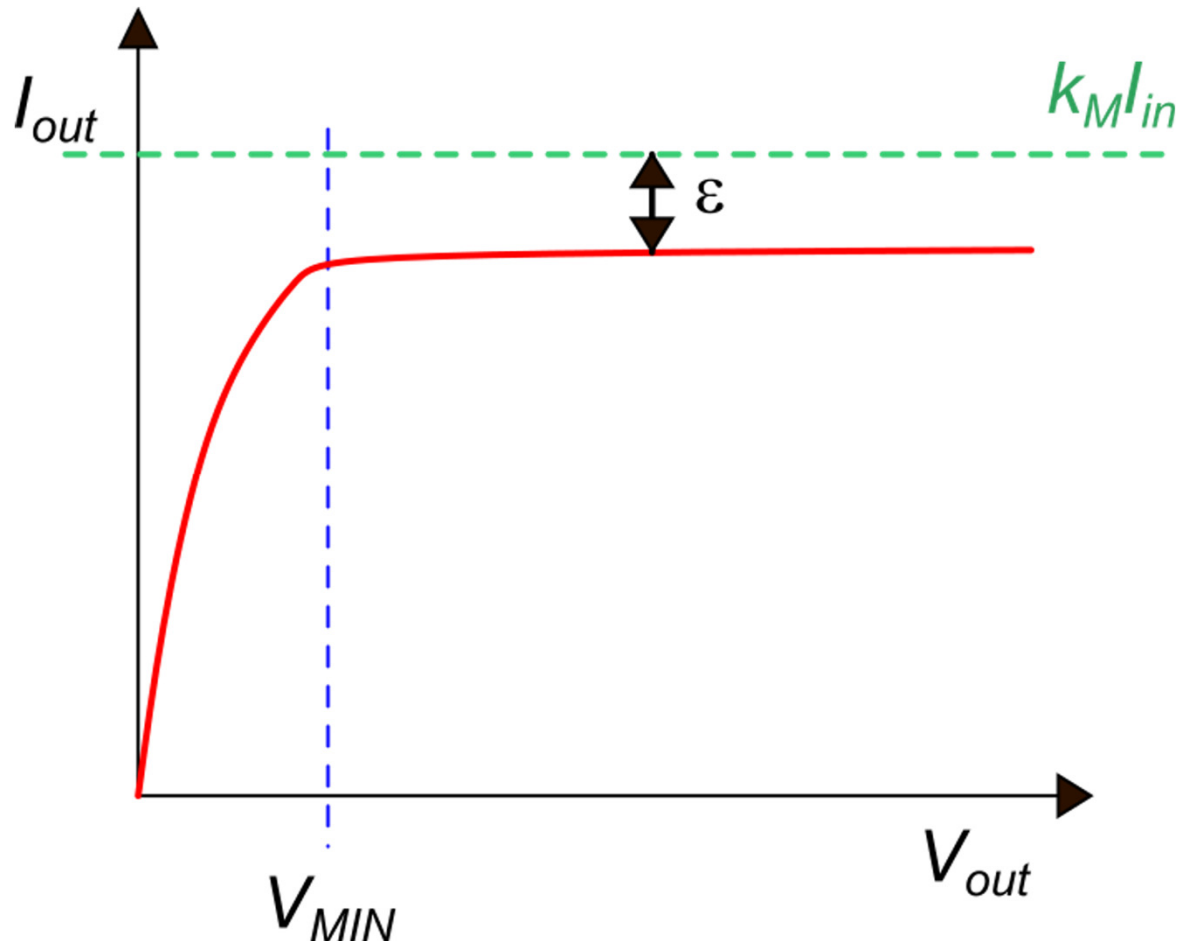
**relative** current variation:

$$\frac{\Delta I_{out}}{I_{out}} = \Delta V_{out} \frac{1}{I_{out} R_{out}} = \frac{\Delta V_{out}}{V_{th}}$$

The Thevenin equivalent voltage allows to compare current mirrors regardless of the current magnitude they are designed for. The higher the Thevenin voltage, the more ideal the current mirror.



## Presence of systematic errors

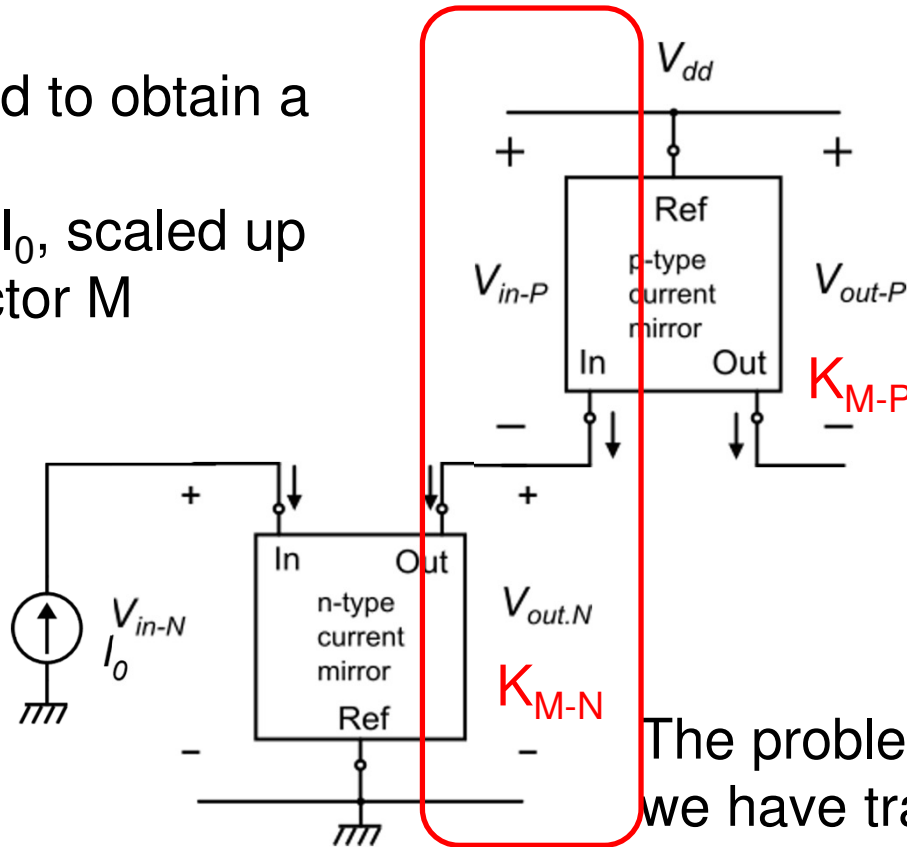


There is not an optimum voltage in the correct operating area ( $V_{out} > V_{MIN}$ ) at which the output current is equal to the ideal value

$k_M$  must be a parameter that can be easily set by design. It is generally a ratio of simple device parameters ( $b$  in MOSFETs, area in BJTs)

## Role of $V_{in}$ , $V_{MIN}$ : an example

We need to obtain a copy of current  $I_0$ , scaled up by a factor  $M$



We add a p-type mirror to reverse the current source type

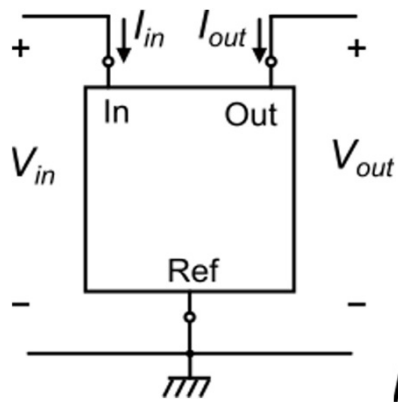
$$M = k_{M-N} k_{M-P}$$

$$V_{dd} = V_{out-N} + V_{in-P}$$

$$\min(V_{dd}) = V_{MIN-N} + V_{in-P}$$

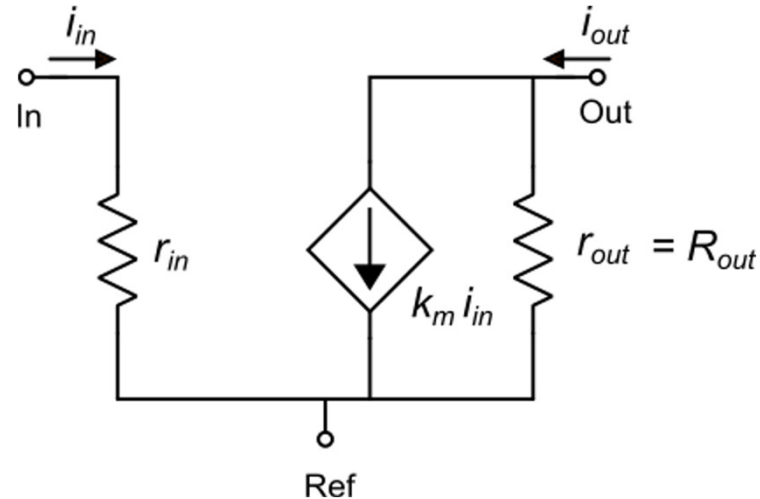
The problem is that we have transformed a source into a sink

# Small signal equivalent circuit of a current mirror

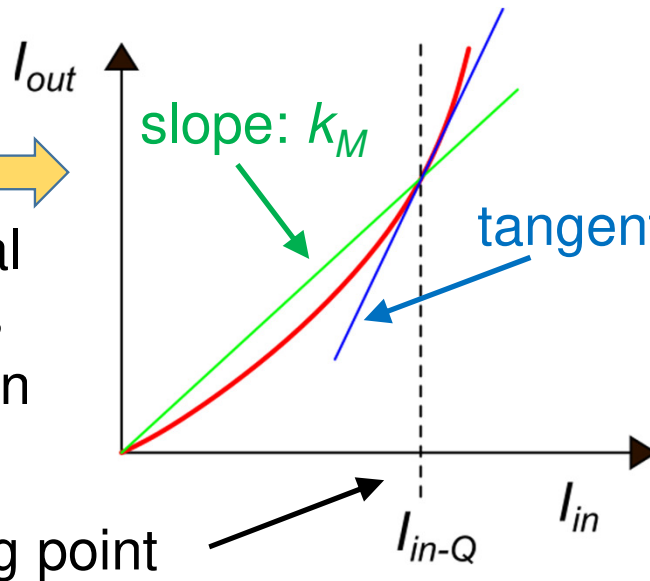


$$k_M = \frac{I_{out}}{I_{in}}$$

$$k_m = \frac{dI_{out}}{dI_{in}}$$

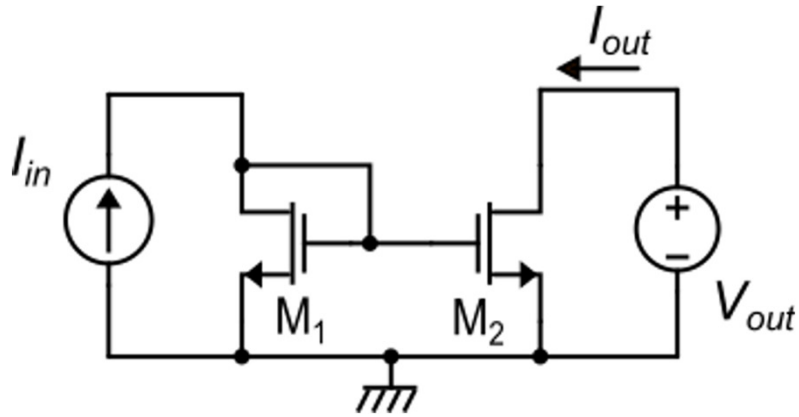


Notice: the linearity of a real current mirror is much better than in this figure



Note: generally  $k_m \neq k_M$

## MOSFET current mirrors: the simple mirror



strong inversion

$$I_D = \beta \frac{(V_{GS} - V_t)^2}{2} [1 + \lambda(V_{DS} - V_{DSAT})]$$

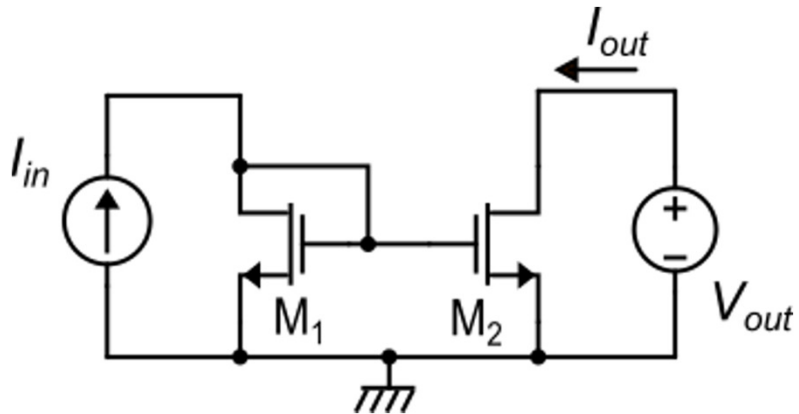
weak inversion

$$I_D = I_{SM} e^{\frac{V_{GS} - V_t}{mV_T}} \left( 1 - e^{\frac{-V_{DS}}{V_T}} \right) [1 + \lambda(V_{DS} - V_{DSAT})]$$

$$I_{SM} = \mu_n C_{ox} (m-1) V_T^2 \frac{W_{eff}}{L_{eff}} = \beta (m-1) V_T^2$$

$$I_D = \beta f(V_{GS} - V_t, V_{DS})$$

## Simple MOSFET current mirror



$$I_D = \beta f (V_{GS} - V_t, V_{DS})$$

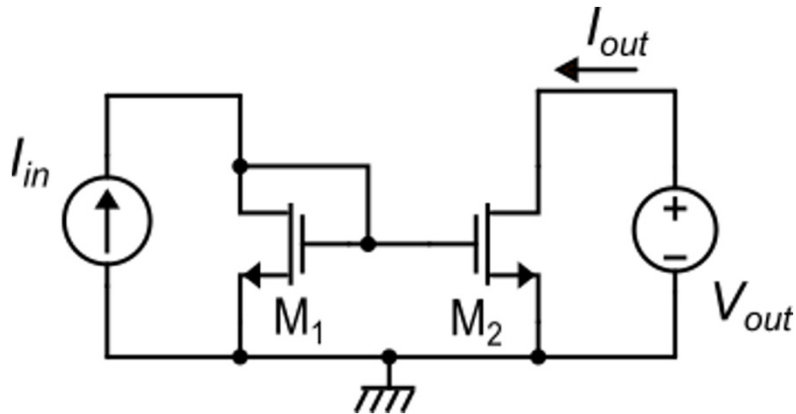
$$I_{out} = \beta_2 f (V_{GS} - V_t, V_{DS2}) = \beta_2 f (V_{GS} - V_t, V_{out})$$

$$I_{in} = \beta_1 f (V_{GS} - V_t, V_{DS1}) = \beta_1 f (V_{GS} - V_t, V_{in})$$

$$\text{For } V_{out} = V_{in} \quad \frac{I_{out}}{I_{in}} = \frac{\beta_2}{\beta_1} = k_M$$

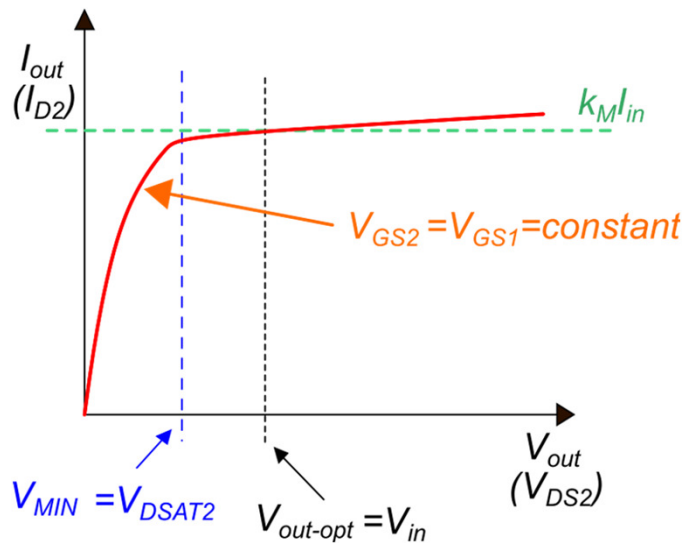
$$V_{out-opt} = V_{in}$$

# Parameters of the simple MOSFET current mirror



$$V_{in} = V_{GS1} = V_t + (V_{GS} - V_t)$$

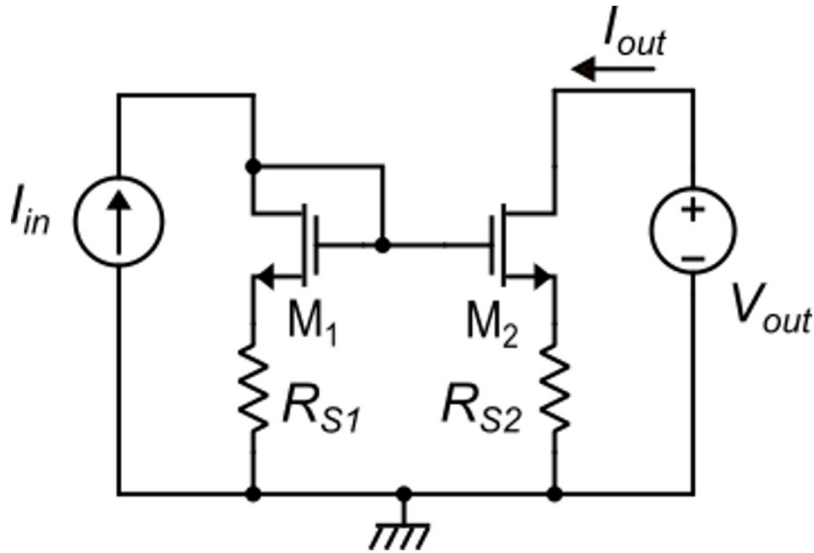
$$V_{MIN} = V_{DSAT2}$$



$$R_{out} = r_{d2} = \frac{1}{\lambda_2 I_{out}}$$

$$V_{th} = I_{out} R_{out} = \frac{1}{\lambda_2}$$

## Increasing $R_{out}$ : source degeneration



$$R_{out} = R_{S2} + r_{d2} (1 + g_{m2} R_{S2})$$

$$R_{out} \cong r_{d2} (1 + g_{m2} R_{S2})$$

The output resistance is increased by a factor  $(1 + g_{m2} R_{S2})$  with respect to the simple current mirror

In order to have a linear behavior, so that  $I_{out} = k_M I_{in}$ , we need that:

Notice:

$$V_{S2} = V_{S1} \Rightarrow R_{S1} I_{in} = R_{S2} I_{out} \quad \leftarrow \quad V_{GS1} = V_{GS2} \Rightarrow \underline{V_{S2} = V_{S1}}$$

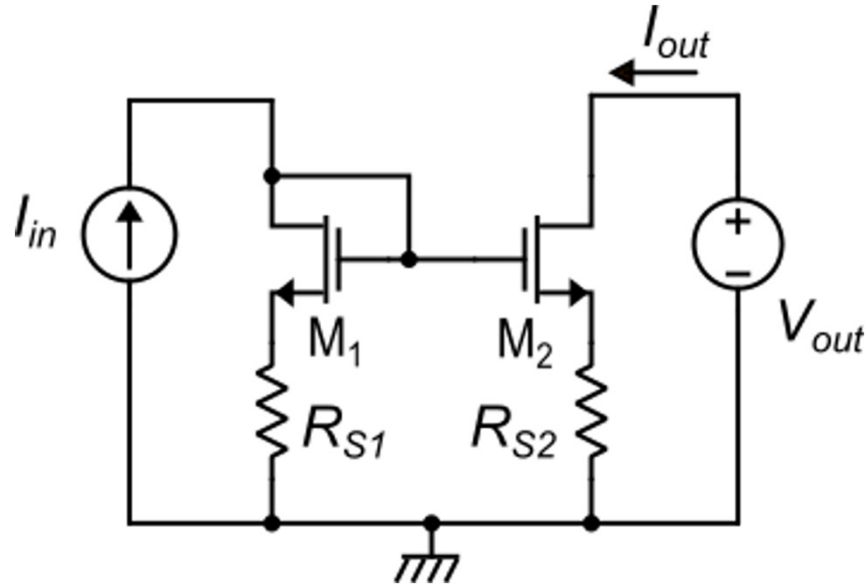
design rule

$$\frac{R_{S1}}{R_{S2}} = \frac{I_{out}}{I_{in}} = k_M$$

In this way, we can apply the same formulas of the simple mirror for  $I_{D1}$  and  $I_{D2}$  that give:

$$k_M = \frac{\beta_2}{\beta_1}$$

## Increasing $R_{out}$ : source degeneration



$$V_{in} = V_{GS1} + R_{S1} I_{in}$$

Notice:  $R_{out} \cong r_{d2} (1 + g_{m2} R_{S2})$

But:  $g_{m2} R_{S2} = \frac{I_{D2} R_{S2}}{V_{TE2}}$

Unfortunately,  $V_{MIN}$  and  $V_{in}$  are larger in this mirror:

$$V_{out} = V_{DS2} + R_2 I_{out}$$

The mirror starts to fail at a  $V_{out}$  value that make  $M_2$  enter triode region

when  $V_{out}$  reduces,  $I_{out}$  is nearly constant, then this term is almost constant and it is  $V_{DS2}$  to diminish.

$$V_{MIN} = V_{DSAT2} + R_2 I_{out}$$

To get a large output resistance boosting factor ( $1 + g_{m2} R_{D2}$ ), it is necessary to make  $R_{D2} I_{out} \gg V_{TE}$

In practice,  $R_{D2} I_{out}$  ( $= R_{D1} I_{in}$ ) cannot be too large to avoid increasing  $V_{in}$  and  $V_{MIN}$  too much